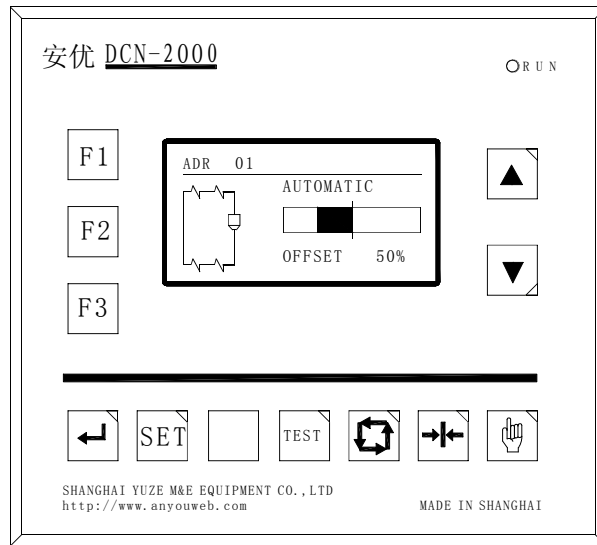
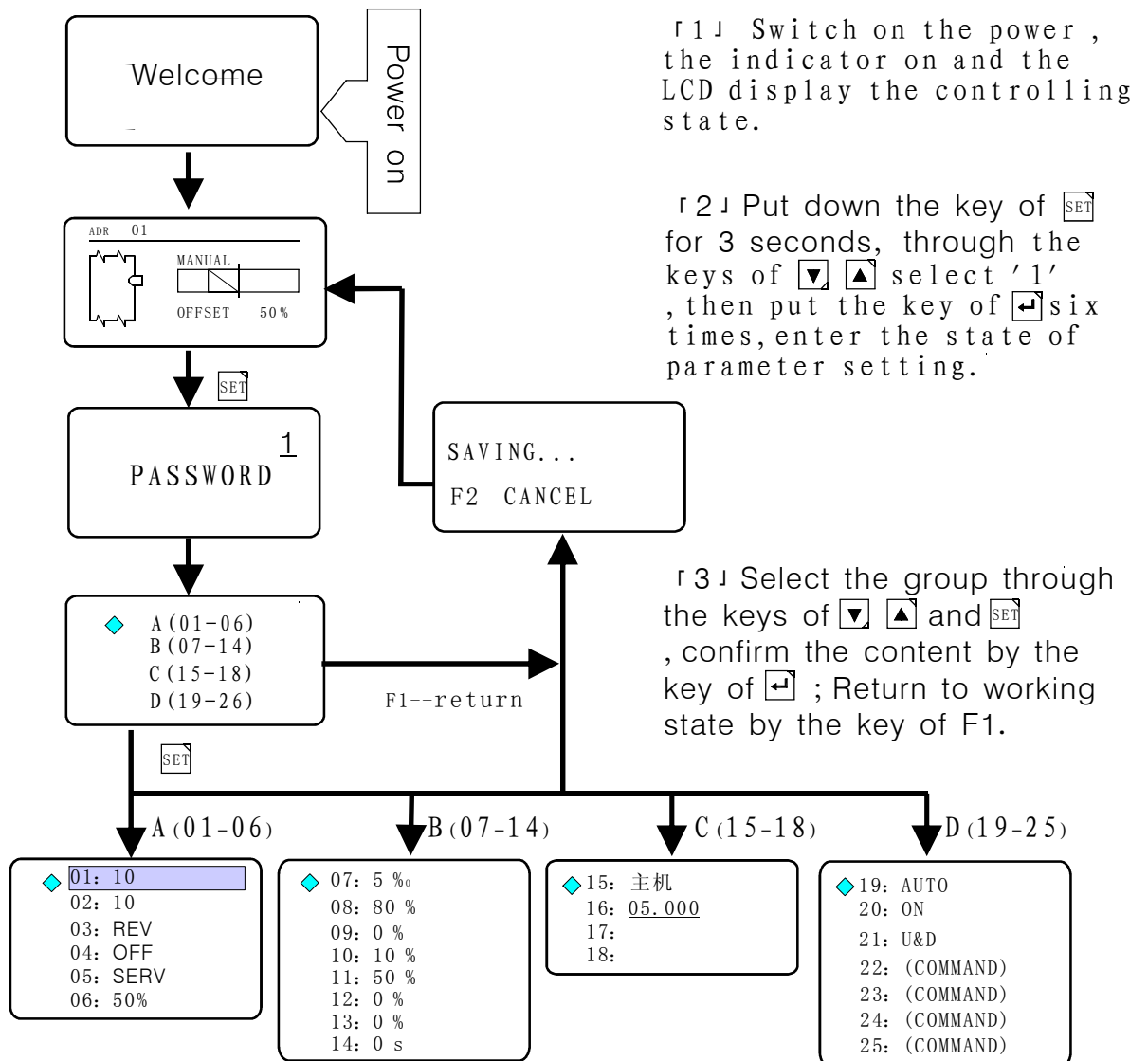


INTERFACE DISCIPTION



PARAMETER SETTING PROCESS



## 2.3 PARAMETER LIST

ITEM	Default	Min	Ma x	Unit	Description
01	1 0	0	3 0	mm/s	In the auto mode, maximum tracking speed
02	1 0	0	3 0	mm/s	In the manual mode, maximum manual speed
03	REV/ FWD				The logical relationship between motor direction and the material deviation
04	DIS/USE				Parking brake function
05	Serv/OUT				Through an external sensor or Operation to reset the actuator
06	5 0 %	0 %	1 0 0 %		The intermediate position occupy the total stroke percentage
07	5 %。	0 %。	1 0 0 %。		The dead zone occupy the total detecting range percentage
08	8 0 %	0 %	1 0 0 %		The acceleration zone occupy the total detecting range percentage
09	0 %	0 %	1 0 0 %		The first acceleration zone occupy the total detecting range percentage
10	1 0 %	0 %	1 0 0 %		The max speed in first acceleration zone occupy the max tracking speed percentage
11	5 0 %	0 %	1 0 0 %		The sensor reference point in the position of the total detecting range
12	0 %	0 %	1 0 0 %		Material damage identification range, beyond this range, start the following speed
13	0 %	0 %	1 0 0 %		Detecting material damage , running speed occupy the max tracking speed percentage
14	1 0 0	0	2 5 5	S	Detecting material damage start timer, beyond this range, the actuator reset
15	SLAV/ MAIN				In the network condition, the host controller can control the subsidiary controller.
16	1	1	3 0		The address of this controller.
17	(指令)				The instruction of establishing communication.
18	0 1	0 1	3 0		The instruction of establishing communication.
19	MAN/ CENT/ AUTO				The state of system when power on
20	DIS/ ONON/ GAP				The output sate of limited alarm
21	* *				The funtion of start /stop port setting .
22	* *				
23	* *				
24	* *				
25	* *				